Algorithmic Logic-Based Verification with SeaHorn

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based on work with Anvesh Komuravelli, and Nikolaj Bjørner

Automated Software Analysis

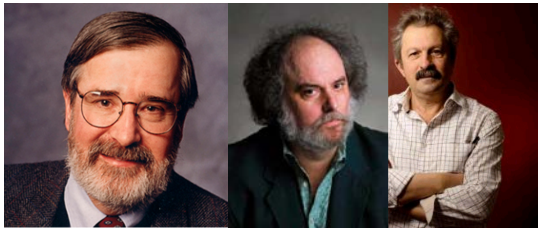
Program → Automated Analysis → Correct / Incorrect

Software Model Checking with Predicate Abstraction

e.g., Microsoft's SDV

Abstract Interpretation with Numeric Abstraction

e.g., ASTREE, Polyspace



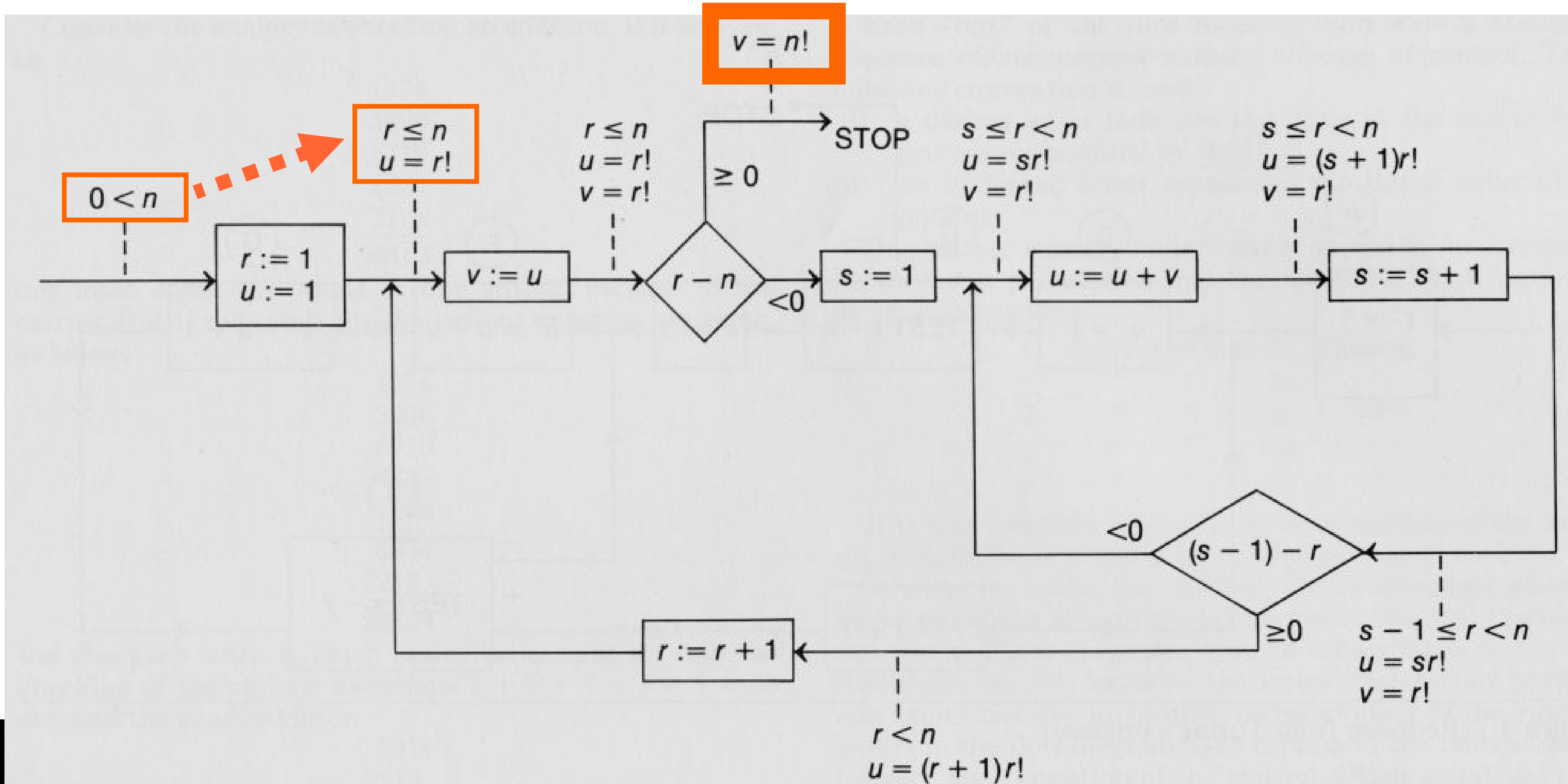
Turing, 1936: “undecidable”

Turing, 1949

Alan M. Turing. “Checking a large routine”, 1949

How can one check a routine in the sense of making sure that it is right?

programmer should make a number of definite assertions which can be checked individually, and from which the correctness of the whole programme easily follows.



Three-Layers of a Program Verifier

Compiler

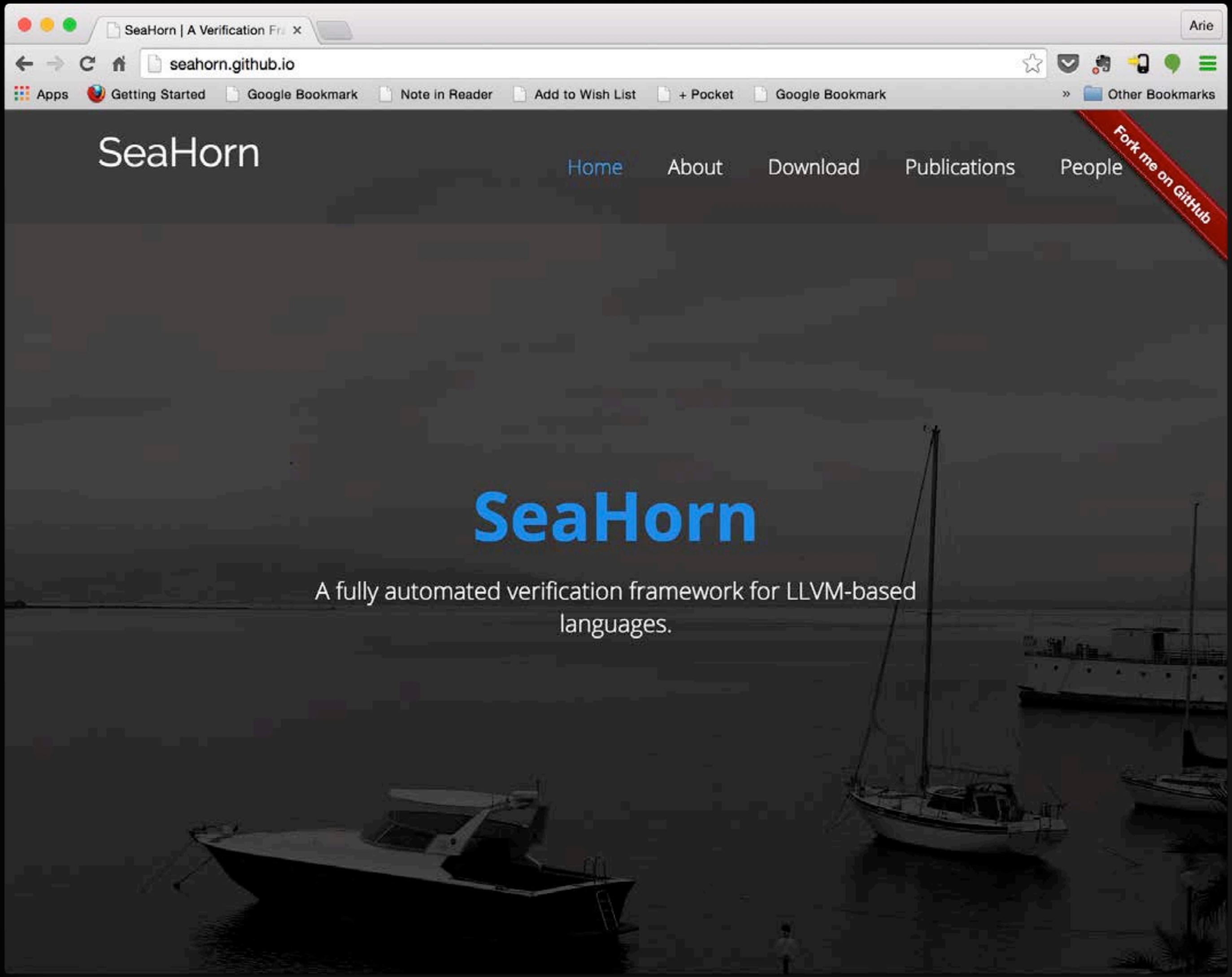
- compiles surface syntax a target machine
- embodies syntax with semantics

Verification Condition Generator

- transforms a program and a property to a verification condition in logic
- employs different abstractions, refinements, proof-search strategies, etc.

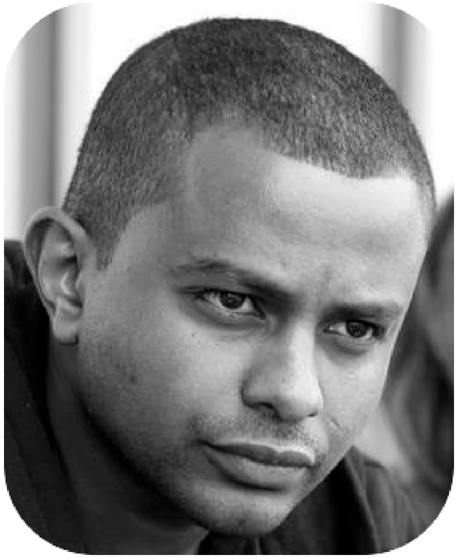
Automated Theorem Prover / Reasoning Engine

- discharges verification conditions
- general purpose constraint solver
- SAT, SMT, Abstract Interpreter, Temporal Logic Model Checker,…



http://seahorn.github.io

SeaHorn Verification Framework



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The Plan

Introduction

Architecture and Usage

Demonstration

Constrained Horn Clauses as an Intermediate Representation

From Programs to Logic

- generating verification conditions

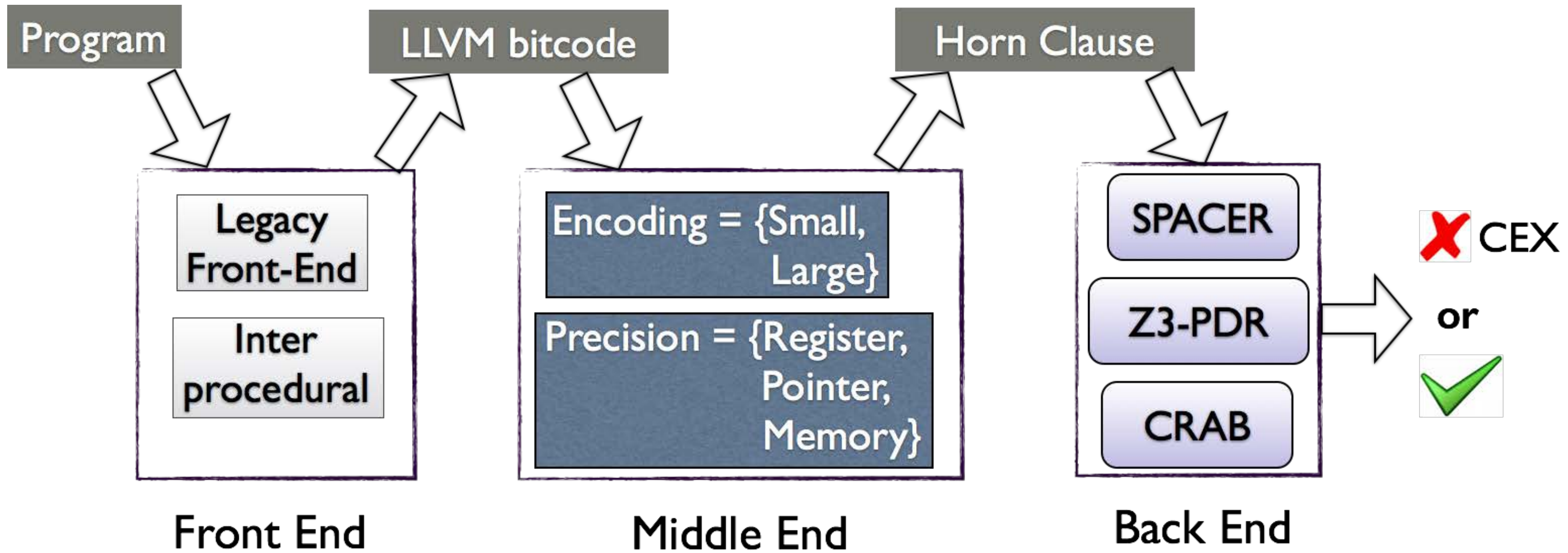
Program Transformations for Verification

Solving Constrained Horn Clauses

- synthesizing inductive invariants and procedure summaries

Conclusion

SeaHorn Verification Framework



Key Features

- LLVM front-end(s)
- Constrained Horn Clauses to represent Verification Conditions
- Comparable to state-of-the-art tools at SV-COMP'15

Goals

- be a state-of-the-art Software Model Checker
- be a framework for experimenting and developing CHC-based verification

Related Tools

CPAChecker

- Custom front-end for C
- Abstract Interpretation-inspired verification engine
- Predicate abstraction, invariant generation, BMC, k-induction

SMACK / Corral

- LLVM-based front-end
- Reduces C verification to Boogie
- Corral / Q verification back-end based on Bounded Model Checking with SMT

UFO

- LLVM-based front-end (partially reused in SeaHorn)
- Combines Abstract Interpretation with Interpolation-Based Model Checking
- (no longer actively developed)

SeaHorn Philosophy

Build a state-of-the-art Software Model Checker

- useful to “average” users
  - user-friendly, efficient, trusted, certificate-producing, …
- useful to researchers in verification
  - modular design, clean separation between syntax, semantics, and logic, …

Stand on the shoulders of giants

- reuse techniques from compiler community to reduce verification effort
  - SSA, loop restructuring, induction variables, alias analysis, …
  - static analysis and abstract interpretation
- reduce verification to logic
  - verification condition generation
  - Constrained Horn Clauses

Build reusable logic-based verification technology

- “SMT-LIB” for program verification

SeaHorn Usage

`> sea pf FILE.c`

Outputs `sat` for unsafe (has counterexample); `unsat` for safe

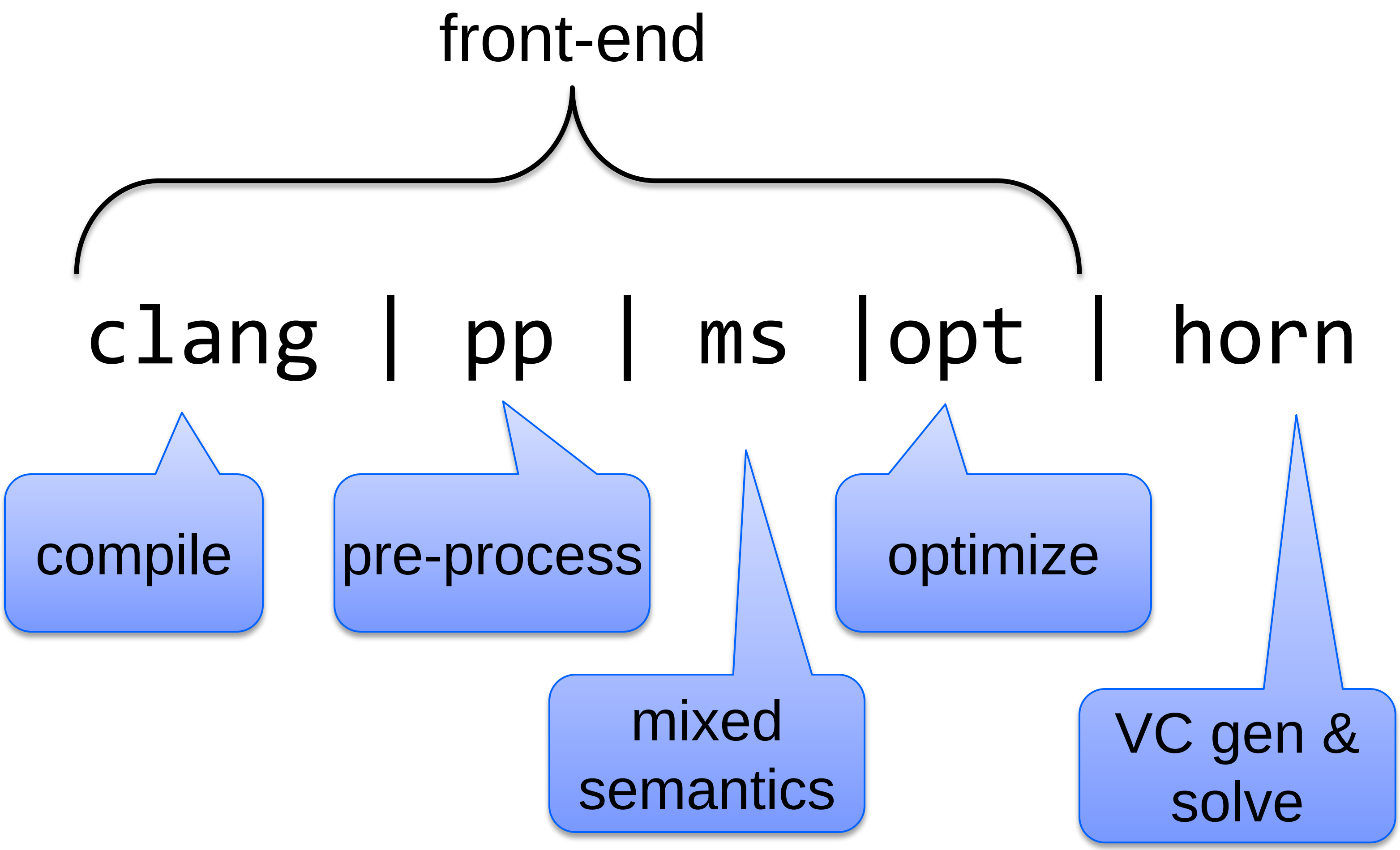
Additional options

- `--cex=trace.xml` outputs a counter-example in SV-COMP'15 format
- --show-invars displays computed invariants
- `--track={reg,ptr,mem}` track registers, pointers, memory content
- `--step={large,small}` verification condition step-semantics
  - *small* == basic block, *large* == loop-free control flow block
- `--inline` inline all functions in the front-end passes

Additional commands

- `sea smt` – generates CHC in extension of SMT-LIB2 format
- `sea clp` -- generates CHC in CLP format (under development)
- `sea lfe-smt` – generates CHC in SMT-LIB2 format using legacy front-end

Verification Pipeline



DEMO

From Programming to Modeling

Extend C programming language with 3 modeling features

Assertions

- assert(e) – aborts an execution when e is false, no-op otherwise

```
void assert (_Bool b) { if (!b) abort(); }
```

Non-determinism

- nondet_int() – returns a non-deterministic integer value

```
int nondet_int () { int x; return x; }
```

Assumptions

- assume(e) – "ignores" execution when e is false, no-op otherwise

```
void assume (_Bool e) { while (!e) ;  }
```

Constrained Horn Clauses

INTERMEDIATE REPRESENTATION

Constrained Horn Clauses (CHC)

A Constrained Horn Clause (CHC) is a FOL formula of the form

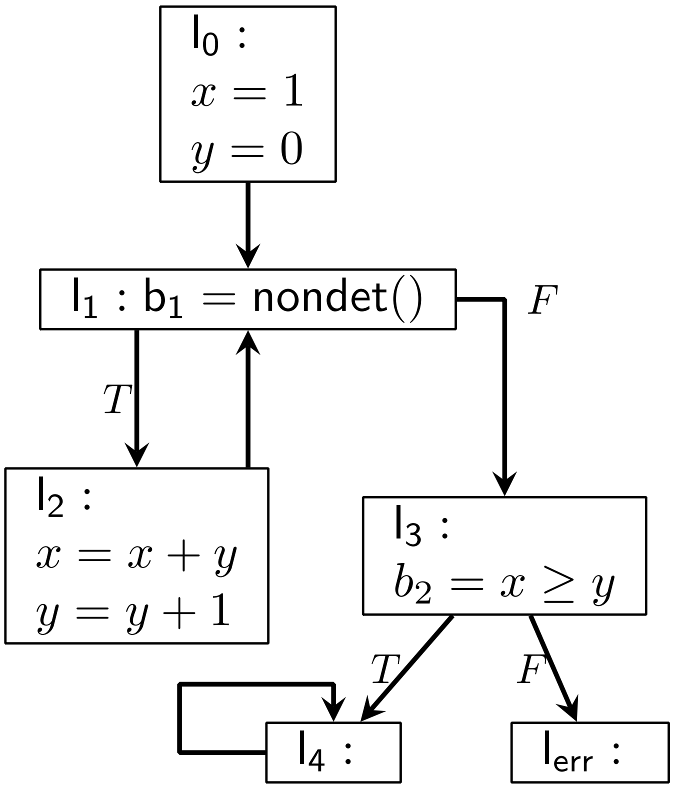
$$8\ V\ .\ (Á\ Æ\ p_1[X_1]\ Æ \ldots Æ\ p_n[X_n] \rightarrow h[X]),$$

where

- A is a background theory (e.g., Linear Arithmetic, Arrays, Bit-Vectors, or combinations of the above)
- Á is a constrained in the background theory A
- $p_1, \ldots, p_n$, h are n-ary predicates
- $p_i[X]$ is an application of a predicate to first-order terms

Example Horn Encoding

int $x = 1$;
int $y = 0$;
while $(*)$ {
    $x = x + y$;
    $y = y + 1$;
}
assert$(x \geq y)$;



$\langle 1 \rangle$ p_0.
$\langle 2 \rangle$ $\mathsf{p}_1(x, y) \leftarrow$
$\quad \mathsf{p}_0, x = 1, y = 0.$
$\langle 3 \rangle$ $\mathsf{p}_2(x, y) \leftarrow \mathsf{p}_1(x, y)$.
$\langle 4 \rangle$ $\mathsf{p}_3(x, y) \leftarrow \mathsf{p}_1(x, y)$.
$\langle 5 \rangle$ $\mathsf{p}_1(x', y') \leftarrow$
$\quad \mathsf{p}_2(x, y),$
$\quad x' = x + y,$
$\quad y' = y + 1.$
$\langle 6 \rangle$ $\mathsf{p}_4 \leftarrow (x \geq y), \mathsf{p}_3(x, y).$
$\langle 7 \rangle$ $\mathsf{p}_{err} \leftarrow (x < y), \mathsf{p}_3(x, y).$
$\langle 8 \rangle$ $\mathsf{p}_4 \leftarrow \mathsf{p}_4.$
$\langle 9 \rangle$ $\bot \leftarrow \mathsf{p}_{err}.$

CHC Terminology

head | body | constraint

Rule $h[X]$ Ã $p_1[X_1], \ldots, p_n[X_n]$, Á.

Query false Ã $p_1[X_1], \ldots, p_n[X_n]$, Á.

Fact $h[X]$ Ã Á.

Linear CHC $h[X]$ Ã $p[X_1]$, Á.

Non-Linear CHC $h[X]$ Ã $p_1[X_1], \ldots, p_n[X_n]$, Á.
for $n > 1$

CHC Satisfiability

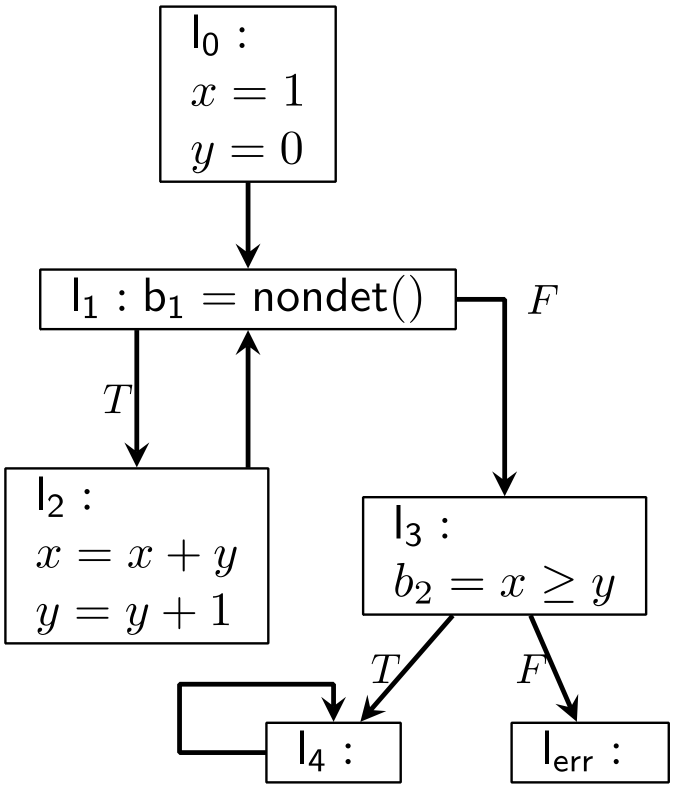
A **model** of a set of clauses ¦ is an interpretation of each predicate p_i that makes all clauses in ¦ valid

A set of clauses is **satisfiable** if it has a model, and is unsatisfiable otherwise

A model is **A-definable**, it each p_i is definable by a formula $\tilde{A}_i$ in A

Example Horn Encoding

int $x = 1;$
int $y = 0;$
while $(*)$ $\{$
    $x = x + y;$
    $y = y + 1;$
$\}$
assert$(x \geq y);$



$\langle 1 \rangle$ $\mathsf{p}_0.$

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Relationship between CHC and Verification

A program satisfies a property iff corresponding CHCs are satisfiable

- satisfiability-preserving transformations == safety preserving

Models for CHC correspond to verification certificates

- inductive invariants and procedure summaries

Unsatisfiability (or derivation of FALSE) corresponds to counterexample

- the resolution derivation (a path or a tree) is the counterexample

CAVEAT: In SeaHorn the terminology is reversed

- SAT means there exists a counterexample – a BMC at some depth is SAT
- UNSAT means the program is safe – BMC at all depths are UNSAT

FROM PROGRAMS TO CLAUSES

Hoare Triples

A Hoare triple {Pre} P {Post} is valid iff every terminating execution of *P* that starts in a state that satisfies *Pre* ends in a state that satisfies *Post*

Inductive Loop Invariant

Pre) Inv {InvÆC} Body {Inv} InvÆ:C) Post

{Pre} **while** C **do** Body {Post}

Function Application

(PreÆp=a)) P {P} Body_F {Q} (QÆp,r=a,b)) Post

{Pre} b = F(a) {Post}

Recursion

{Pre} b = F(a) {Post} ` {Pre} Body_F {Post}

{Pre} b = F(a) {Post}

Weakest Liberal Pre-Condition

Validity of Hoare triples is reduced to FOL validity by applying a **predicate transformer**

Dijkstra's weakest liberal pre-condition calculus [Dijkstra'75]

wlp (P, Post)

weakest pre-condition ensuring that executing P ends in Post

{Pre} P {Post} is valid , Pre) **wlp** (P, Post)

A Simple Programming Language

```
Prog  ::= def Main(x) { body_M }, …, def P (x) { body_P }

body  ::= stmt (; stmt)*

stmt  ::= x = E | assert (E) | assume (E) |
          while E do S | y = P(E) |
          L:stmt | goto L               (optional)

E     := expression over program variables
```

Horn Clauses by Weakest Liberal Precondition

`Prog ::=` **`def`** `Main(x) { body`$_M$ `}, …,` **`def`** `P (x) { body`$_P$ `}`

wlp (x=E, Q) = **let** x=E **in** Q

wlp (**assert**(E) , Q) = E Æ Q

wlp (**assume**(E), Q) = E → Q

wlp (**while** E **do** S, Q) = I(w) Æ

8w . ((I(w) Æ E) → wlp (S, I(w))) Æ ((I(w) Æ :E) → Q))

wlp (y = P(E), Q) = p_{pre}(E) Æ (8 r. p(E, r) → Q[r/y])

ToHorn (**def** P(x) {S}) = wlp (x0=x;**assume**(p_{pre}(x)); S, p(x0, ret))

ToHorn (Prog) = wlp (Main(), true) Æ 8{P 2 Prog} . ToHorn (P)

Example of a WLP Horn Encoding

```
{Pre: y¸ 0}
 xo = x;
 yo = y;
 while y > 0 do
   x = x+1;
   y = y−1;
{Post: x=xo+yo}
```

ToHorn

```
C1: I(x,y,x,y) Ã y¸0.
C2: I(x+1,y-1,xo,yo) Ã I(x,y,xo,yo), y>0.
C3: false Ã I(x,y,xo,yo), y·0, x≠xo+yo
```

{y ¸ 0} P {x = x_{old}+y_{old}} is **true** iff the query C_3 is **satisfiable**

Example Horn Encoding

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int $y = 0$;
while $(*)$ {
    $x = x + y$;
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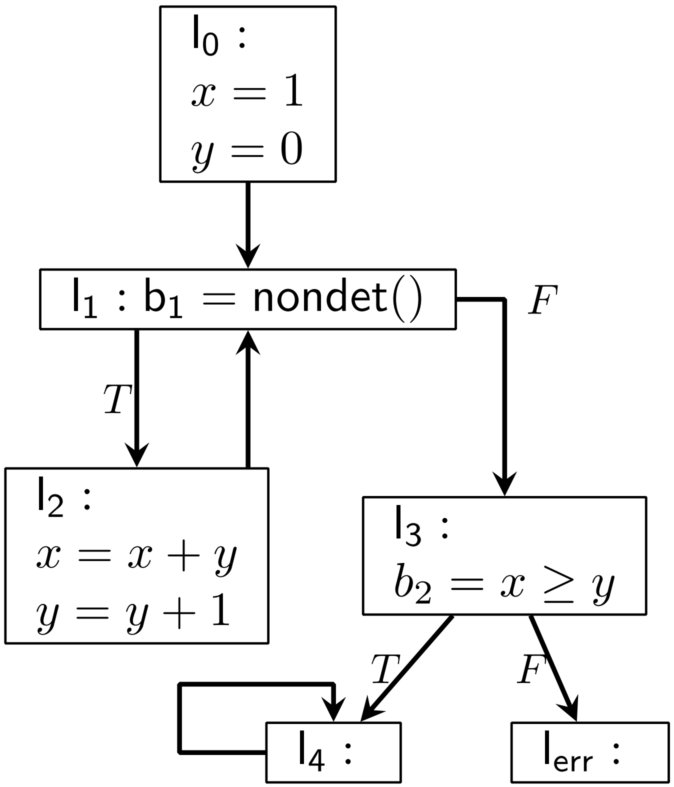
}
assert$(x \geq y)$;



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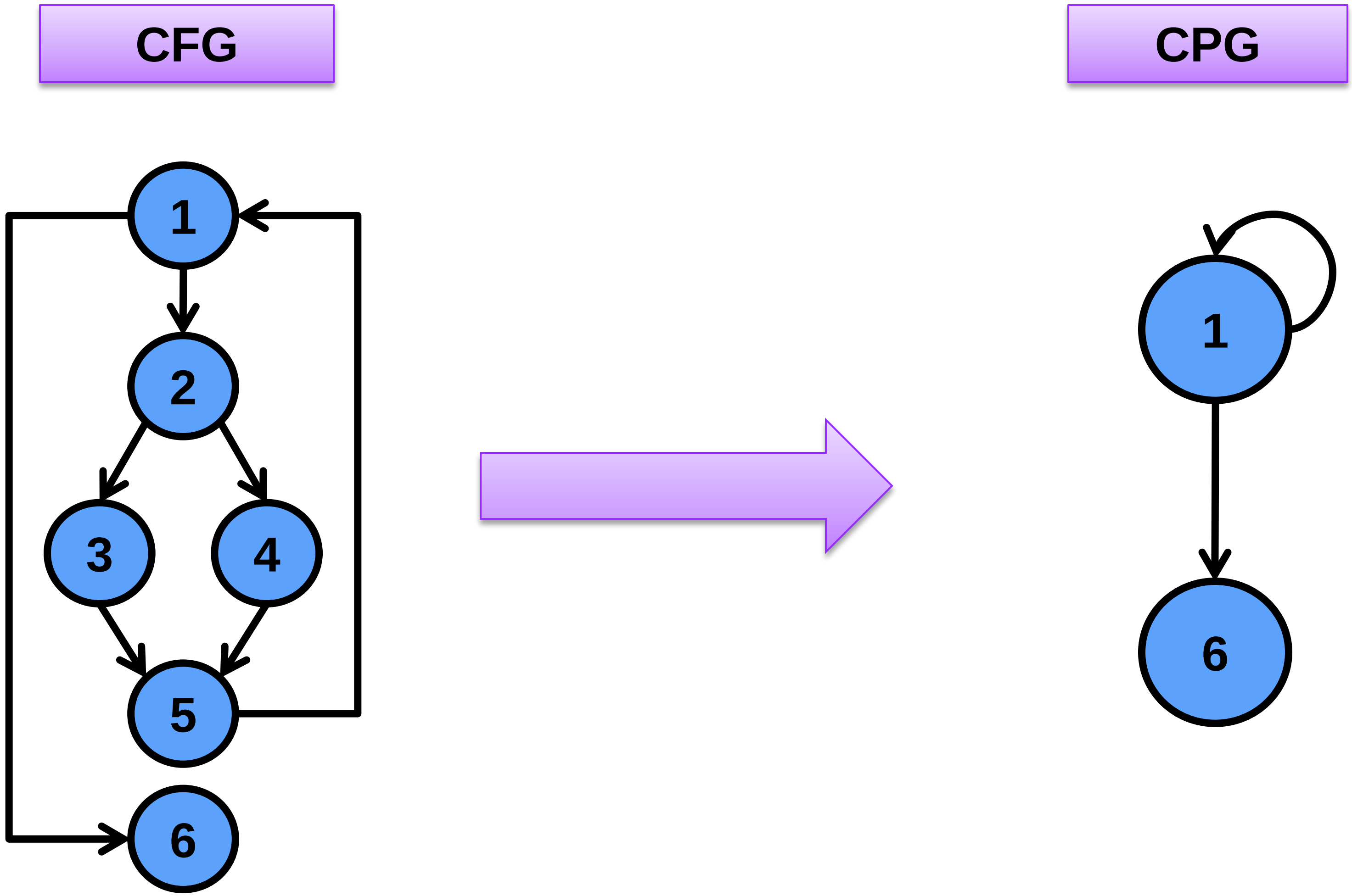
From CFG to Cut Point Graph

A *Cut Point Graph* hides (summarizes) fragments of a control flow graph by (summary) edges

Vertices (called, *cut points*) correspond to *some* basic blocks

An edge between cut-points *c* and *d* summarizes all finite (loop-free) executions from *c* to *d* that do not pass through any other cut-points

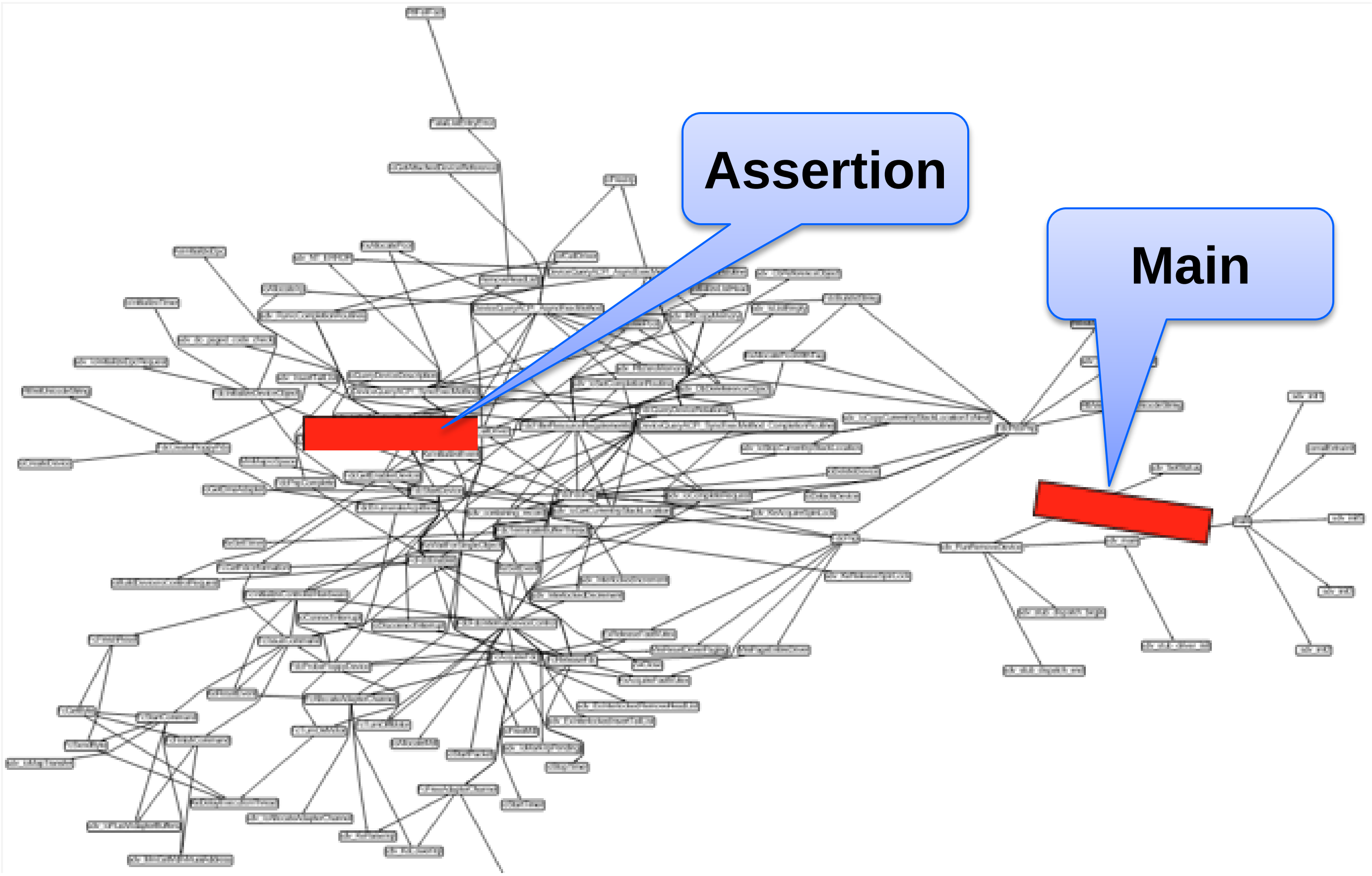
Cut Point Graph Example



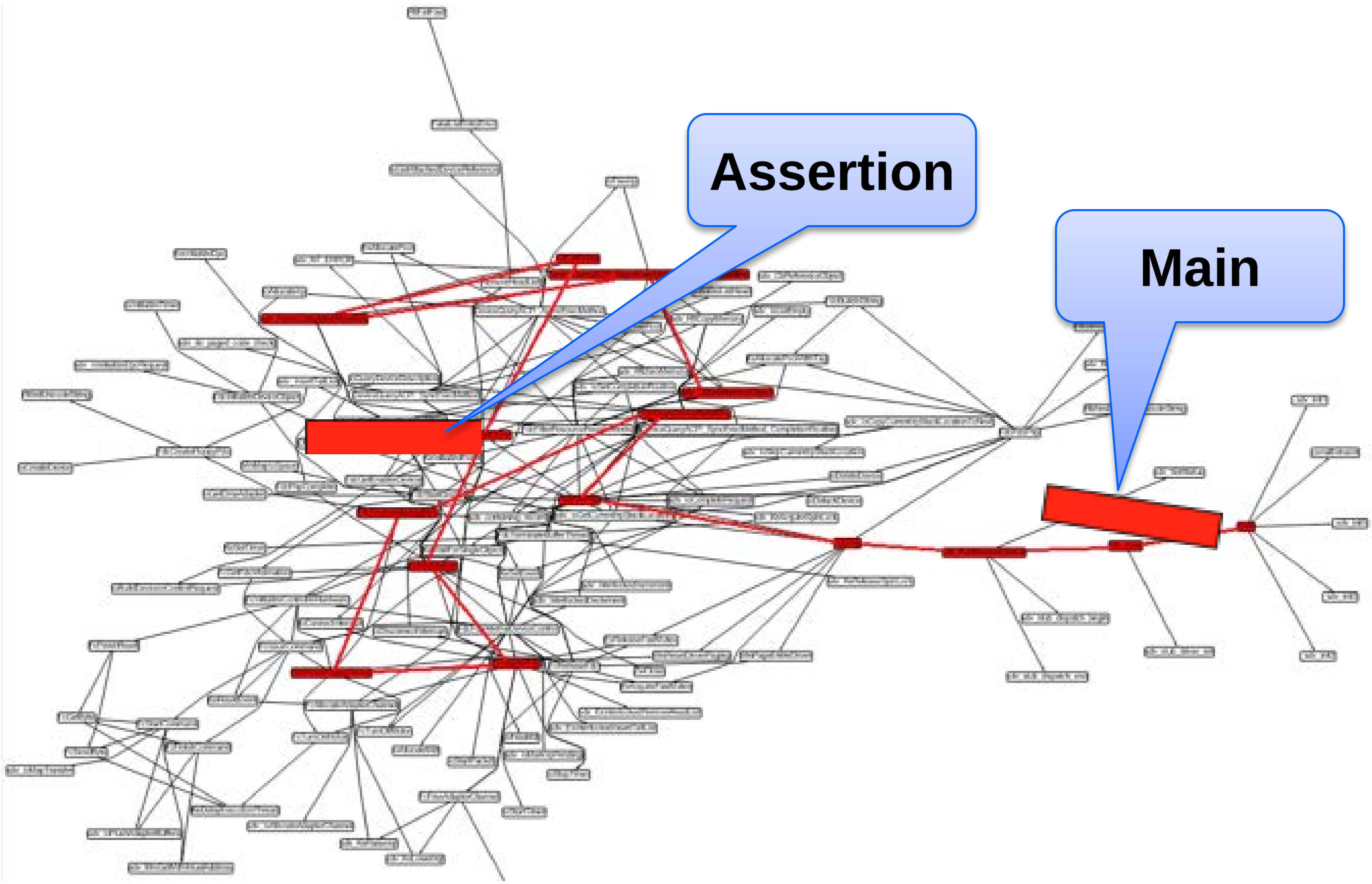
Mixed Semantics

PROGRAM TRANSFORMATION

Deeply nested assertions



Deeply nested assertions



Counter-examples are long

Hard to determine (from main) what is relevant

Mixed Semantics

[GWC'08,LQ'14]

Stack-free program semantics combining:

- operational (or small-step) semantics
  - i.e., usual execution semantics
- natural (or big-step) semantics: function summary [Sharir-Pnueli 81]
  - (¾, ¾`) 2 ||f|| iff the execution of f on input state ¾ terminates and results in state ¾'
- some execution steps are big, some are small

Non-deterministic executions of function calls

- update top activation record using function summary, or
- enter function body, forgetting history records (i.e., no return!)

Preserves reachability and non-termination

Theorem: Let K be the operational semantics, K^m the stack-free semantics, and L a program location. Then,

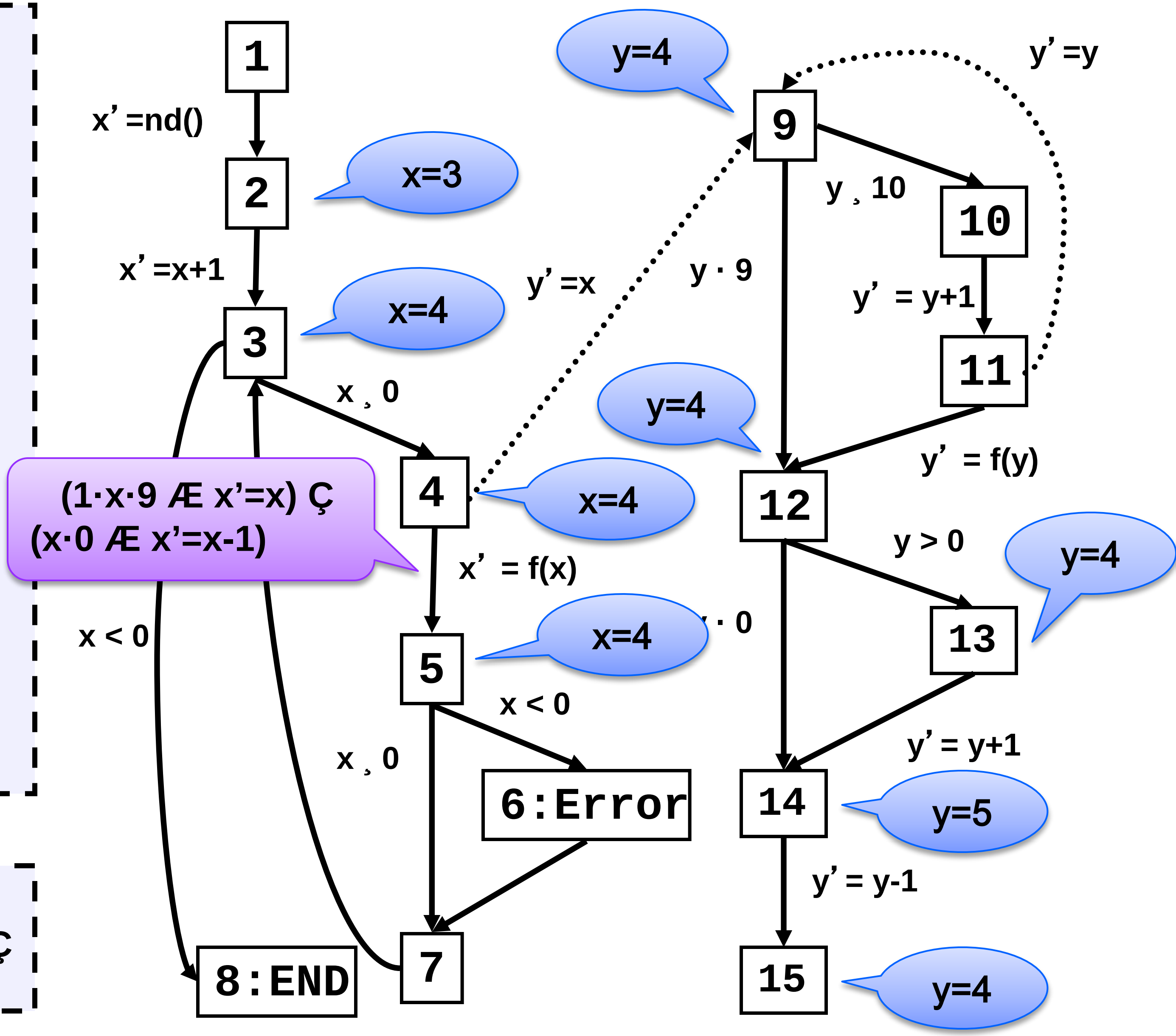
K ² EF (pc=L) , K^m ² EF (pc=L) and K ² EG (pc≠L) , K^m ² EG (pc≠L)

```
def main()
1: int x = nd();
2: x = x+1;
3: while(x>=0)
4:   x=f(x);
5:   if(x<0)
6:      Error;
7:
8: END;

def f(int y): ret y
9:  if(y¸10){
10:     y=y+1;
11:     y=f(y);
12: else if(y>0)
13:    y=y+1;
14: y=y-1
15:
```

Summary of f(y)

(1·y·9 Æ y' =y) Ç
(y·0 Æ y' =y-1)



Mixed Semantics as Program Transformation

```
main ()
    p1 (); p1 ();
    assert (c1);
p1 ()
    p2 ();
    assert (c2);
p2 ()
    assert (c3);
```

Mixed Semantics

```
main_new ()
    if (*) goto p1_entry;
    else p1_new ();
    if (*) goto p1_entry;
    else p1_new ();
    if (¬c1) goto error;
    assume (false);

p1_entry :
    if (*) goto p2_entry;
    else p2_new ();
    if (¬c2) goto error;
p2_entry :
    if (¬c3) goto error;
    assume (false);
error : assert (false);

p1_new ()
    p2_new ();
    assume (c2);
p2_new ()
    assume (c3);
```

Mixed Semantics: Summary

Every procedure is inlined at most once

- in the worst case, doubles the size of the program
- can be restricted to only inline functions that directly or indirectly call errror() function

Easy to implement at compiler level

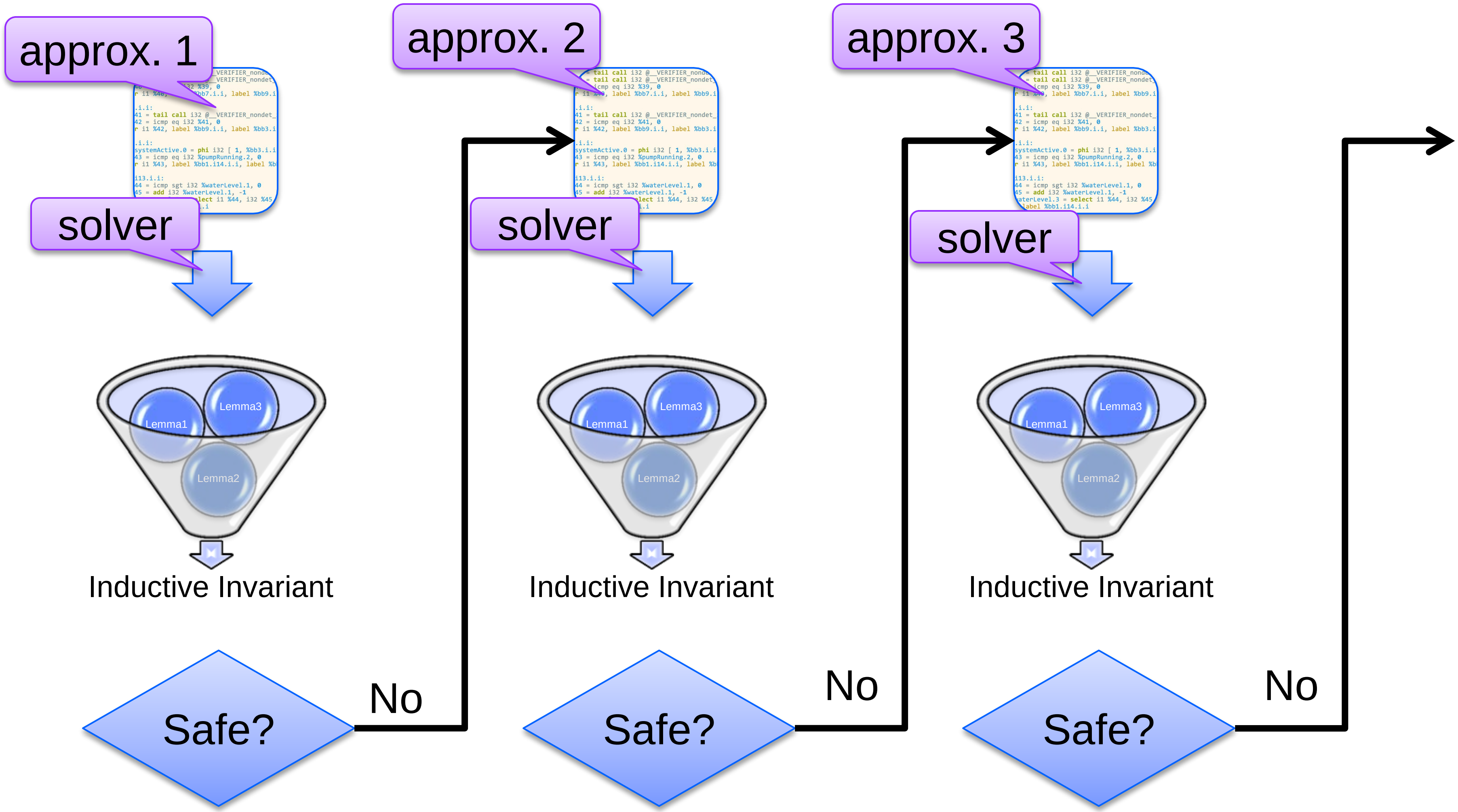
- create “failing” and “passing” versions of each function
- reduce “passing” functions to returning paths
- in main(), introduce new basic block bb.F for every failing function F(), and call failing.F in bb.F
- inline all failing calls
- replace every call to F to non-deterministic jump to bb.F or call to passing F

Increases context-sensitivity of context-insensitive analyses

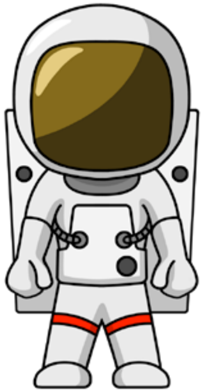
- context of failing paths is explicit in main (because of inlining)
- enables / improves many traditional analyses

SOLVING CHC WITH SMT

Verification by Evolving Approximations



Spacer: Solving CHC in Z3



Spacer: solver for SMT-constrained Horn Clauses

- stand-alone implementation in a fork of Z3
- http://bitbucket.org/spacer/code

Support for Non-Linear CHC

- model procedure summaries in inter-procedural verification conditions
- model assume-guarantee reasoning
- uses MBP to under-approximate models for finite unfoldings of predicates
- uses MAX-SAT to decide on an unfolding strategy

Supported SMT-Theories

- Best-effort support for arbitrary SMT-theories
  - data-structures, bit-vectors, non-linear arithmetic
- Full support for Linear arithmetic (rational and integer)
- Quantifier-free theory of arrays
  - only quantifier free models with limited applications of array equality

CRAB: Cornucopia of Abstractions

A library of abstract domains build on top of NASA Ikos (Inference Kernel for Open Static Analyzers)

A language-independent intermediate representation

Many abstract domains

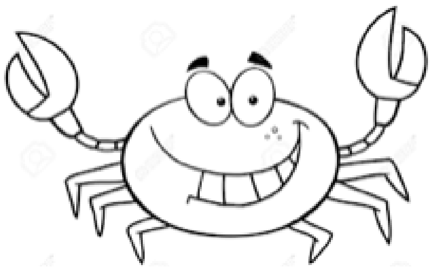
- intervals (with congruences) (with uninterpreted functions)
- zones, dbms, octagons
- pointer analysis with offsets
- array analysis with smashing

Fixpoint iteration library

- precise interleaving between widening and narrowing
- extensible with thresholds

Efficient reusable data-structure

- simple API for integrating new abstract domains



RESULTS

SV-COMP 2015

http://sv-comp.sosy-lab.org/2015/

4th Competition on Software Verification held (here!) at TACAS 2015

Goals

- Provide a snapshot of the state-of-the-art in software verification to the community.
- Increase the visibility and credits that tool developers receive.
- Establish a set of benchmarks for software verification in the community.

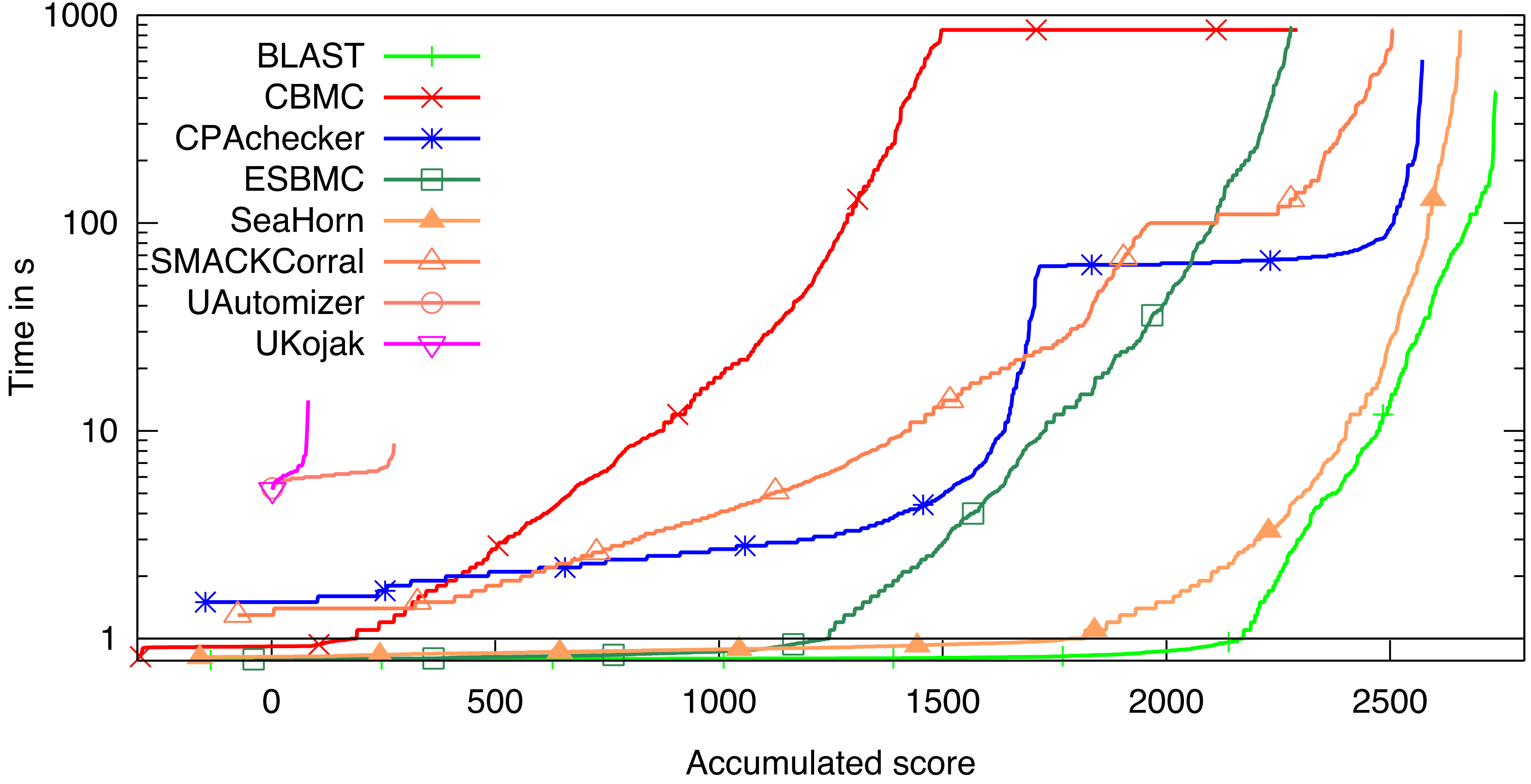
Participants:

- Over 22 participants, including most popular Software Model Checkers and Bounded Model Checkers

Benchmarks:

- C programs with error location (programs include pointers, structures, etc.)
- Over 6,000 files, each 2K – 100K LOC
- Linux Device Drivers, Product Lines, Regressions/Tricky examples
- http://sv-comp.sosy-lab.org/2015/benchmarks.php

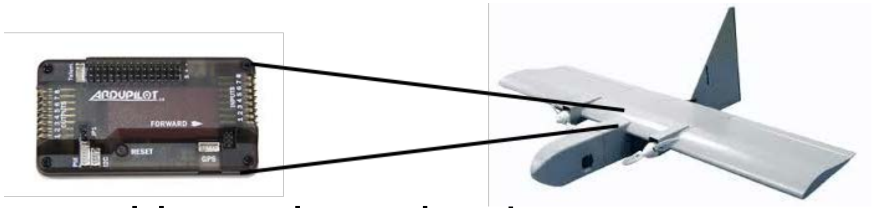
Results for DeviceDriver category



Detecting Buffer Overflow in Auto-pilot software

Show absence of Buffer Overflows in

- paparazzi and mnav autopilots

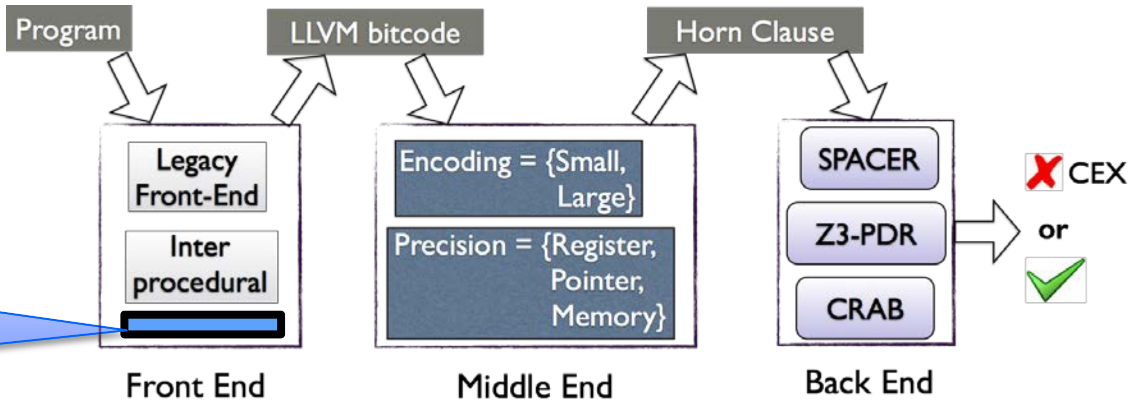


Automatically instrument buffer accesses with runtime checks

Use SeaHorn to validate that run-time checks never fail

- somewhat slower than pure abstract interpretation
- much more precise!

LLVM Pass to insert BO checks



Conclusion

SeaHorn (http://seahorn.github.io)

- a state-of-the-art Software Model Checker
- LLVM-based front-end
- CHC-based verification engine
- a framework for research in logic-based verification

The future

- making SeaHorn useful to users of verification technology
  - counterexamples, build integration, property specification, proofs, etc.
- targeting many existing CHC engines
  - specialize encoding and transformations to specific engines
  - communicate results between engines
- richer properties
  - termination, liveness, synthesis

Available postdoctoral positions

What: development and application of SeaHorn

Where: CMU/NASA Silicon Valley Campus

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Programs, Cexs, Invariants

A program *P = (V, Init, ½, Bad)*

- Notation: F(X) = 9 ***u*** . (X Æ ½) Ç Init

P is UNSAFE if and only if there exists a number *N* s.t.

$$Init(v_0) \wedge \left(\bigwedge_{i=0}^{N-1} \rho(v_i, v_{i+1}) \right) \wedge Bad(v_N) \not\Rightarrow \bot$$

P is SAFE if and only if there exists a *safe inductive invariant* *Inv* *s.t.*

$$Init(u) \Rightarrow Inv(u)$$

$$Inv(u) \wedge \rho(u, v) \Rightarrow Inv(v)$$

} Inductive

$$Inv(u) \Rightarrow \neg Bad(u)$$

Safe

IC3/PDR Algorithm Overview

bounded safety

Input: Safety problem $\langle \mathit{Init}(X), \mathit{Tr}(X, X'), \mathit{Bad}(X) \rangle$

$F_0 \leftarrow \mathit{Init}\ ; N \leftarrow 0$ **repeat**

$\quad \mathbf{G} \leftarrow \textsc{PdrMkSafe}([F_0, \ldots, F_N], \mathit{Bad})$

$\quad$ **if** $\mathbf{G} = [\,]$ **then return** $\mathit{Reachable}$;

$\quad \forall 0 \leq i \leq N \cdot F_i \leftarrow \mathbf{G}[i]$

$\quad F_0, \ldots, F_N \leftarrow \textsc{PdrPush}([F_0, \ldots, F_N])$

$\quad$ **if** $\exists 0 \leq i < N \cdot F_i = F_{i+1}$ **then return** $\mathit{Unreachable}$;

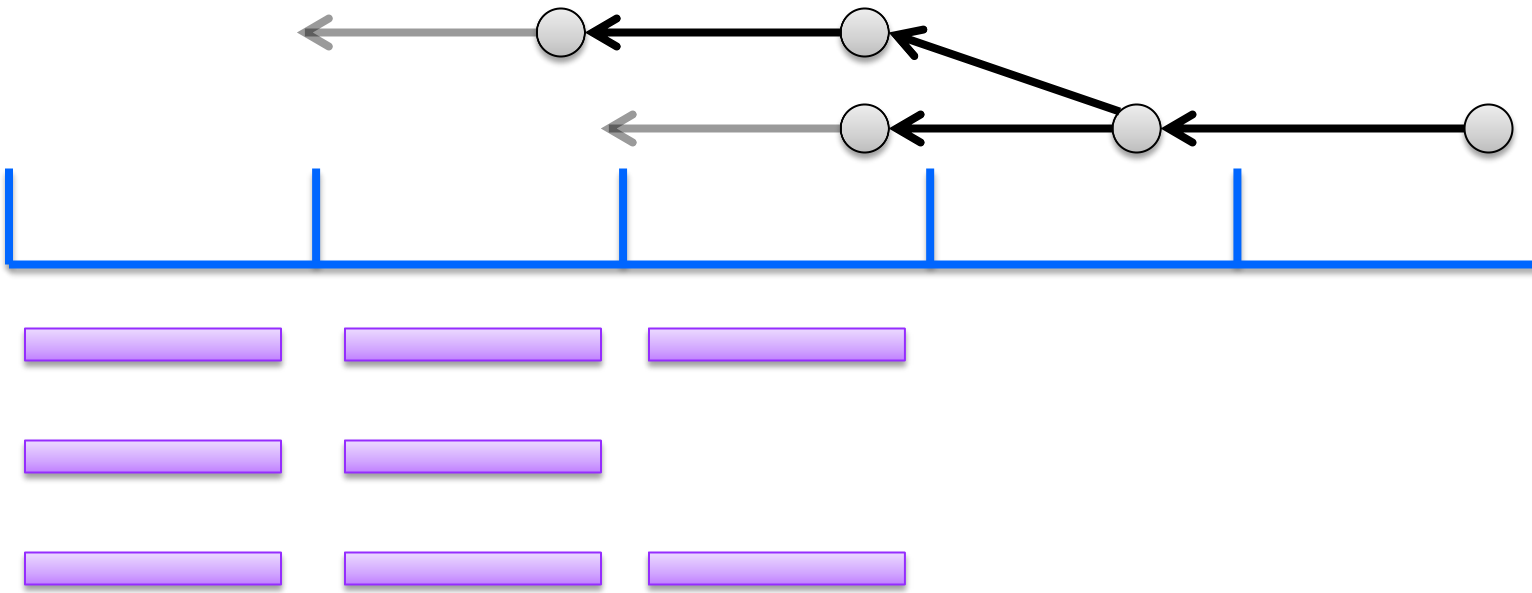
$\quad N \leftarrow N + 1\ ; F_N \leftarrow \emptyset$

until ∞;

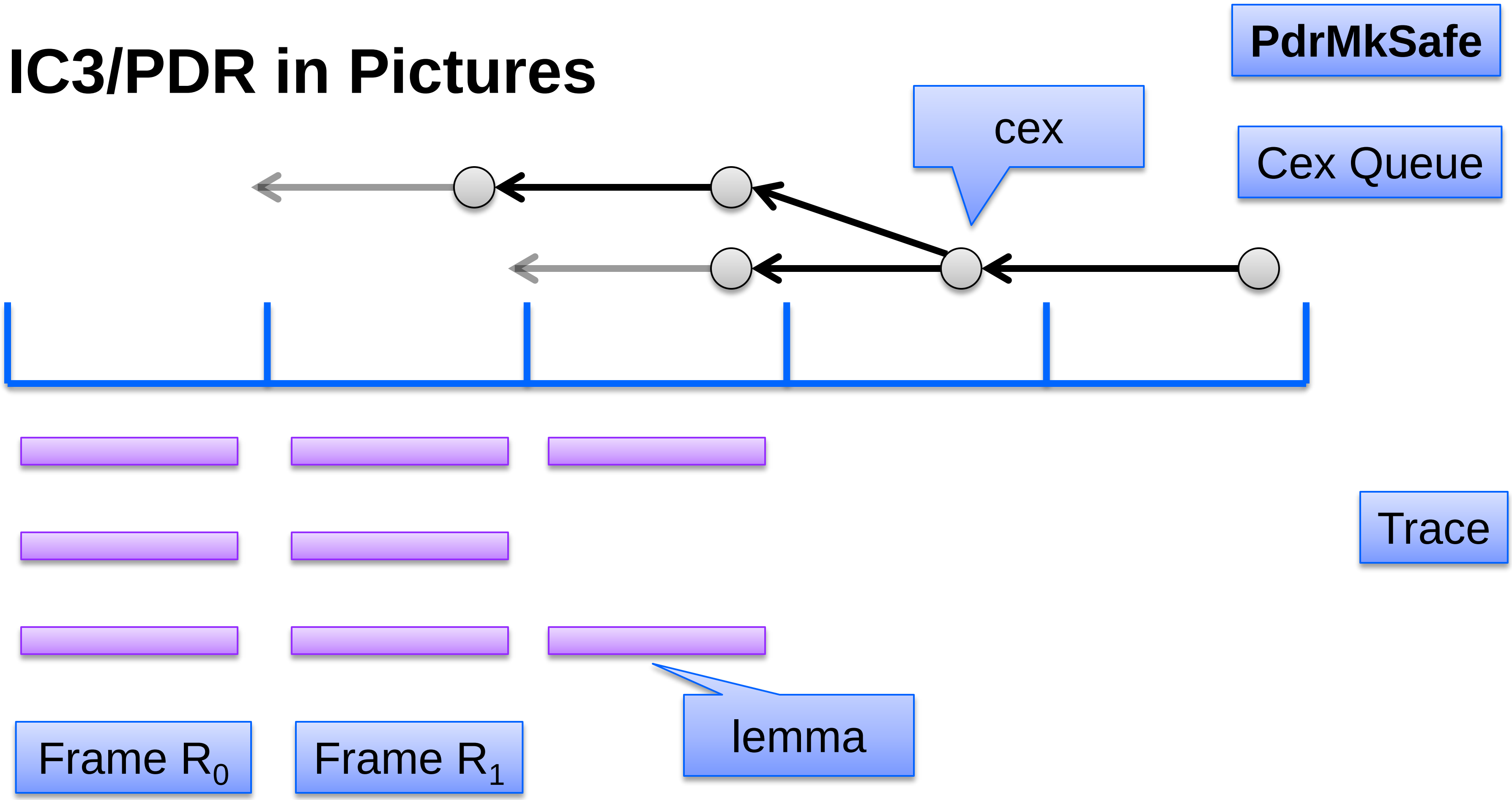
strengthen result

IC3/PDR in Pictures

PdrMkSafe

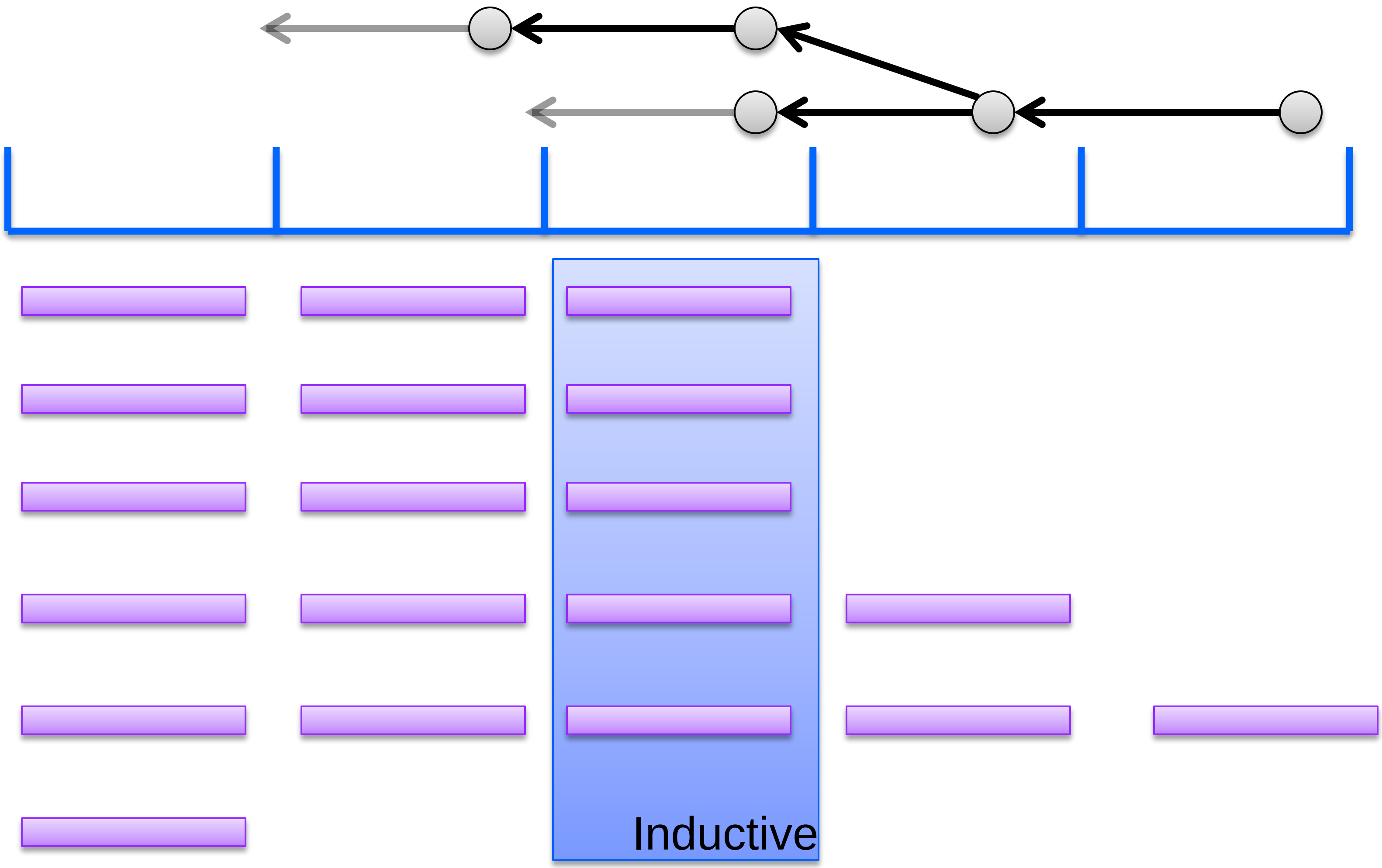


IC3/PDR in Pictures



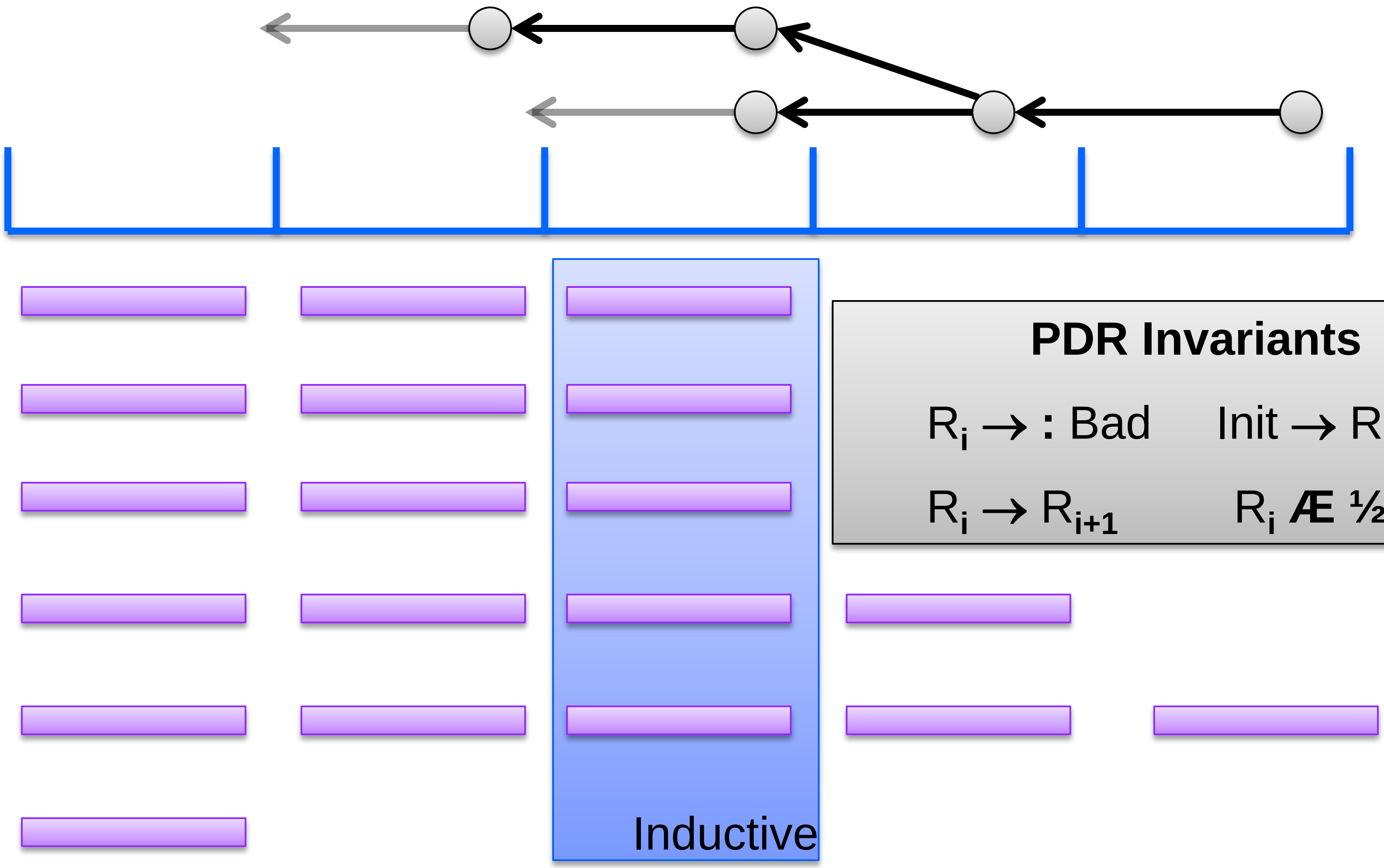
IC3/PDR in Pictures

PdrPush



IC3/PDR in Pictures

PdrPush



PDR Invariants

R_i → : Bad   Init → R_i

R_i → R_{i+1} R_i Æ ½ → R_{i+1}